

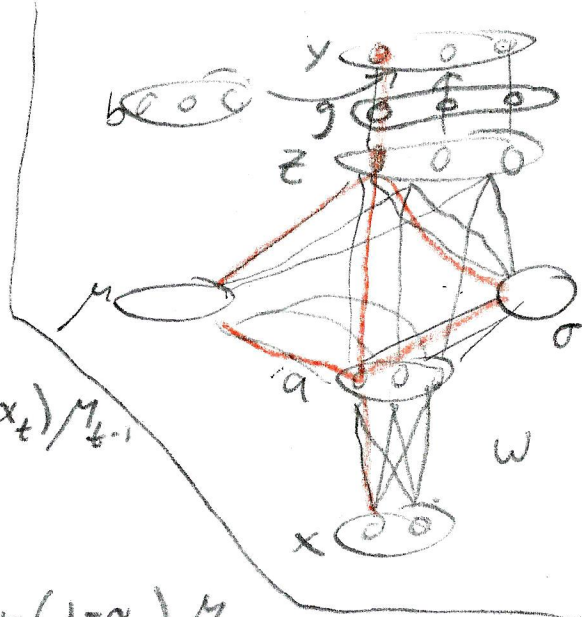
Layer Norm : $y = g \odot z + b$

Where: $\underline{z}_0 = \frac{a_0 - \mu_t}{\sigma_t}$

$$a_0 = \sum_i \underline{w}_{0i} x_i$$

$$\mu_t = \frac{\alpha_t}{D} \sum_p a_p + (1 - \alpha_t) \mu_{t-1}$$

$$\sigma_t = \alpha_t \sqrt{\frac{1}{D-1} \sum_p (a_0 - \mu_t)^2} + (1 - \alpha_t) \sigma_{t-1}$$



• Averages

• Learnable

$$D = n_{out}$$

$$m = \frac{1}{D} \sum_p a_p$$

So: $\mu_t = \alpha_t m + (1 - \alpha_t) \mu_{t-1}$

Goal: At time t , what are the gradients of the inputs and params: $\frac{\partial L}{\partial x_i}$, $\frac{\partial L}{\partial b_0}$, $\frac{\partial L}{\partial g_0}$, $\frac{\partial L}{\partial w_{0i}}$

Using chain rule, we can find the partials at every connection of the graph and combine.

$$\frac{\partial y_0}{\partial g_0} = z_0$$

$$\frac{\partial y_0}{\partial b_0} = 1$$

$$\frac{\partial y_0}{\partial z_0} = g_0$$

Prelim: Quotient Rule : $\frac{\partial}{\partial x} \left(\frac{g(x)}{h(x)} \right) = \frac{h(x) \frac{\partial}{\partial x} g(x) - g(x) \frac{\partial}{\partial x} h(x)}{h(x)^2}$

There is an alternate formulation which is more convenient for us here:

$$\frac{\partial}{\partial x} \left(\frac{g(x)}{h(x)} \right) = \frac{1}{h(x)} \cdot \frac{\partial}{\partial x} g(x) - \frac{g(x)}{h(x)^2} \frac{\partial}{\partial x} h(x)$$

The gradient flows from $z_0 \rightarrow a_p$ in 3 ways...
 directly $z_0 \rightarrow a_0$, and indirectly through μ_t and σ_t .
 This means when we compute $\frac{\partial z_0}{\partial x_i}$ or $\frac{\partial z_0}{\partial w_{pi}}$ that we
 need to sum over these pathways.

$$\frac{\partial z_0}{\partial a_p} = \frac{\partial}{\partial a_p} \left(\frac{a_0 - \mu_t}{\sigma_t} \right)$$

Note: Use quotient rule with
 $g(x) = a_0 - \mu_t$ $h(x) = \sigma_t$

$$= \frac{1}{\sigma_t} \frac{\partial}{\partial a_p} (a_0 - \mu_t) - \frac{a_0 - \mu_t}{\sigma_t^2} \frac{\partial}{\partial a_p} \sigma_t = \frac{1}{\sigma_t} \left[1_{0=p} - \frac{\partial \mu_t}{\partial a_p} - \frac{z_0}{\sigma_t} \frac{\partial \sigma_t}{\partial a_p} \right]$$

Indicator is
 1 when $0=p$
 So we need $\frac{\partial \mu_t}{\partial a_p}$ and $\frac{\partial \sigma_t}{\partial a_p}$. Let's derive those:

$$\frac{\partial \mu_t}{\partial a_p} = \frac{\alpha_t}{D}$$

$$\frac{\partial \sigma_t}{\partial a_p} = \alpha_t \frac{\partial}{\partial a_p} \left(\frac{1}{D-1} \sum_q (a_q - \mu_t)^2 \right)^{1/2}$$

$$= \alpha_t \cdot \left(\frac{1}{2} \right) \cdot \underbrace{\left(\frac{1}{D-1} \sum_q (a_q - \mu_t)^2 \right)^{-1/2}}_{\sigma_t} \cdot \frac{\partial}{\partial a_p} \left(\frac{1}{D-1} \sum_q (a_q - \mu_t)^2 \right)$$

$$= \frac{\alpha_t}{2\sigma_t} \cdot \frac{1}{D-1} \cdot \sum_q \frac{\partial}{\partial a_p} (a_q - \mu_t)^2$$

$$= \frac{\alpha_t}{2\sigma_t(D-1)} \cdot \sum_q \left[2 \cdot (a_q - \mu_t) \cdot \frac{\partial}{\partial a_p} (a_q - \mu_t) \right]$$

$$\frac{\partial \sigma_t}{\partial a_p} = \frac{\alpha_t}{\sigma_t(D-1)} \cdot 2 \cdot \sum_q (a_q - \mu_t) \left[\underbrace{\frac{\partial a_q}{\partial a_p}}_{1_{p=q}} - \underbrace{\frac{\partial \mu_t}{\partial a_p}}_{\frac{\alpha_t}{D}} \right]$$

$$= \frac{\alpha_t}{\sigma_t(D-1)} \left[(a_p - \mu_t) - \frac{\alpha_t}{D} \sum_q (a_q - \mu_t) \right]$$

$$= \frac{\alpha_t}{D-1} \cdot z_p - \frac{\alpha_t^2}{\sigma_t D(D-1)} \left[\sum_q a_q - \underbrace{\sum_q \mu_t}_{D \mu_t} \right]$$

$$= \frac{\alpha_t}{D-1} z_p - \frac{\alpha_t^2}{\sigma_t(D-1)} \mu_t - \frac{\alpha_t^2}{\sigma_t(D-1)} \left(\frac{1}{D} \sum_q a_q \right)$$

$$\frac{\partial \sigma_t}{\partial a_p} = \frac{\alpha_t}{D-1} \cdot \left[z_p - \underbrace{\frac{\alpha_t}{\sigma_t} \left(\mu_t - \frac{1}{D} \sum_q a_q \right)}_{\mu_t}$$

Difference of online mean vs.
this timestep's mean

Back to computing $\frac{\partial z_0}{\partial a_p} \dots$

$$\frac{\partial z_0}{\partial a_p} = \frac{1}{\sigma_t} \left[1_{0=p} - \frac{\partial \mu_t}{\partial a_p} - z_0 \frac{\partial \sigma_t}{\partial a_p} \right]$$

$$= \frac{1}{\sigma_t} \left[1_{0=p} - \frac{\alpha_t}{D} - z_0 \left(\frac{\alpha_t}{D-1} \right) \left[z_p - \alpha_t \cdot \frac{\mu_t - m}{\sigma_t} \right] \right]$$

$$\frac{\partial z_0}{\partial a_p} = \frac{1}{\sigma_t} \left[1_{0=p} - \alpha_t \left[\frac{1}{D} + \frac{z_0 z_p}{D-1} - \alpha_t z_0 \left(\frac{\mu_t - m}{\sigma_t} \right) \right] \right]$$

$$\frac{\partial a_p}{\partial x_i} = w_{pi}$$

$$\frac{\partial a_p}{\partial w_{qi}} = 1_{p=q} \cdot x_i$$

The formulas we really care about are $\frac{\partial L}{\partial x_i}$ and $\frac{\partial L}{\partial w_{ji}}$:

$$\frac{\partial L}{\partial x_i} = \sum_0 \frac{\partial L}{\partial y_0} \cdot \frac{\partial y_0}{\partial x_i} = \sum_0 \frac{\partial L}{\partial y_0} \frac{\partial y_0}{\partial z_0} \frac{\partial z_0}{\partial x_i} = \sum_0 \nabla_{y_0} \cdot g_0 \cdot \frac{\partial z_0}{\partial x_i}$$

$$\frac{\partial L}{\partial w_{ji}} = \dots = \sum_0 \nabla_{y_0} \cdot g_0 \cdot \frac{\partial z_0}{\partial w_{ji}}$$

need these

$$\frac{\partial z_0}{\partial x_i} = \sum_p \frac{\partial z_0}{\partial a_p} \underbrace{\frac{\partial a_p}{\partial x_i}}_{w_{pi}} = \sum_p w_{pi} \frac{\partial z_0}{\partial a_p}$$

$$\frac{\partial L}{\partial x_i} \stackrel{\text{rearrange}}{=} \sum_p w_{pi} \cdot \underbrace{\left(\sum_0 \nabla_{y_0} g_0 \frac{\partial z_0}{\partial a_p} \right)}_{\nabla_{a_p}}$$

$$\nabla_{x_i} = \sum_p \nabla_{a_p} w_{pi}$$

$$\frac{\partial L}{\partial w_{ji}} = \sum_p \nabla_{a_p} \frac{\partial a_p}{\partial w_{ji}} = \sum_p \nabla_{a_p} \left(\mathbb{1}_{p=j} x_i \right)$$

$$\nabla_{w_{ji}} = \nabla_{a_j} \cdot x_i$$

Backprop Affine w/o bias!

Conclusion:

- Split Layer Norm into $\underbrace{a \rightarrow y}_{\text{norm}}$ and $\underbrace{x \rightarrow a}_{\text{linear}}$.
- Compute $\nabla g, \nabla b, \nabla a$ in the norm layer.
- Compute $\nabla w, \nabla x$ in the linear layer using backprop eqs and no bias.

$$\nabla a_p = \sum_0 \frac{\partial L}{\partial z_0} \frac{\partial z_0}{\partial a_p} = \sum_0 \underbrace{\frac{\partial L}{\partial y_0}}_{\nabla y_0} \cdot \underbrace{\frac{\partial y_0}{\partial z_0}}_{g_0} \cdot \frac{\partial z_0}{\partial a_p}$$

$$\nabla a_p = \sum_0 \nabla y_0 g_0 \cdot \left(\frac{\partial z_0}{\partial a_p} \right)$$

$$\nabla g_0 = \nabla y_0 \cdot z_0$$

$$\nabla b_0 = \nabla y_0$$